

Virtual Robot Application: Developed at IIT Delhi

DH Parameters of Kuka KR5 Robot (Home Position)

Joint	Joint Offset b (mm)	Joint Angle θ (degree)	Link Length a (mm)	Twist Angle α (degree)
1	400	0 (variable)	180	90
2	0	90 (variable)	600	0
3	0	0 (variable)	120	90
4	620	0 (variable)	0	90
5	0	270 (variable)	0	90
6	115	-180 (variable)	0	0